

Jack (Jianxiang) Xu

- 📍 JXproject
- 🏠 jxinbox.com
- 📁 Jack-xu-jxinbox
- 📞 (289) 242 7243
- ✉️ j337xu@edu.uwaterloo.ca

Mechatronics Engineering I 2A

University of Waterloo | B.A.S c (2016 - 2021)

SKILLS

- Hardware:** • LabVIEW, Arduino, ESP8266, ARM boards, PLC, EAGLE, Soldering, Rapid Prototyping
- Software:** • C, C++, Java, C#, Python, VBA script, Javascript
- Mechanical:** • SolidWorks, VectorWorks, Fusion 360, AutoCAD, Laser Cutting, 3D printing
- Tools/Platforms:** • Unity, Linux, OpenCV, TensorFlow, Git, IAR Embedded Workbench

EXPERIENCE

- Embedded Developer**
Baanto, Nytric Inc.
(May 2017 - Aug. 2017)
 - Developed firmware in **C++** to compute vertices and recognize the shape of basic polygons precisely for ShadowSense multi-touch screen
 - Proposed and created new analyzing tool sets in **Excel** with **VBA** and a real-time monitoring tool in **Unity** with **C#**, to decrease debug time through improved presentation of sensor data
- Lead Hardware Developer**
TobyX (Startup)
(May. 2017 - present)
 - Developing a new dynamically scalable IoT solution for hotel services and advertising, composing of Cloud, Hubs, and Things to provide a revolutionary experience
 - Designing and prototyping embedded hardware such as outlets, thermostats, and hub devices with secure wifi communication in **C/C++**

PROJECTS

- TrackyAI**
(Sept. 2017)
 - Built a surveillance processing tool (for Canadian Special Operations Forces Command) that allows military analysts to better evaluate large amounts of video footage
 - Implemented image processing and object recognition with **Python**, **OpenCV**, and **TensorFlow**
- Extensa Robotic Arm**
(Nov. 2016)
 - Designed and built a robotic arm with 4 degrees of freedom with **Lego NXT**, Tetrax Kit, **C++** and **RobotC**
 - Implemented PID control, inverse kinematics, auto calibration, voice feedback and Bluetooth functionality onto the arm for a more interactive and seamless control interface
- Project Helm**
(Feb. 2017)
 - A smart IoT helmet for bikers that provides haptic feedback for any approaching vehicles.
 - LED strips were used to provide visual cues to approaching vehicles when stopping, accelerating, and turning
 - Used **C++**, Xadow Kit, Accelerometer, and other electronic components
- Music Walker**
(Oct. 2016)
 - Designed and built a music line follower which converts greyscale colour line to music with low-cost homemade greyscale sensors, using **C++** and **Arduino**
- Music Synthesizer**
(Jan. 2017)
 - Created a music synthesizer, using **Arduino**, Gyro, and other electronic components from scratch within 12 hours, which won 2nd place in IEEE Hackathon
- Robot and Control System Projects**
(Feb. 2016)
 - Built a variety of prototypes such as a microwave, a multi-floor elevator, a green house, and a vehicle lift with **STEM kits** and **myDAQ**, programmed in **LabVIEW**
 - Won 1st place in Halton Skills Competition for robotic and control system design

ACTIVITIES

- UW Robotic Team**
(Sept. 2016 - present)
 - Worked on the mechanical and electrical design for an autonomous Mars Rover robot
 - Currently working on firmware development for the new 2018 Mars Rover robot
- FRC 3161 Team**
 - Designed mechanical systems for First Robotic Competition. (Currently working as a Mentor)
- Photography**
 - An unique way of retrieving myself back to the nature